

FIGURE 1

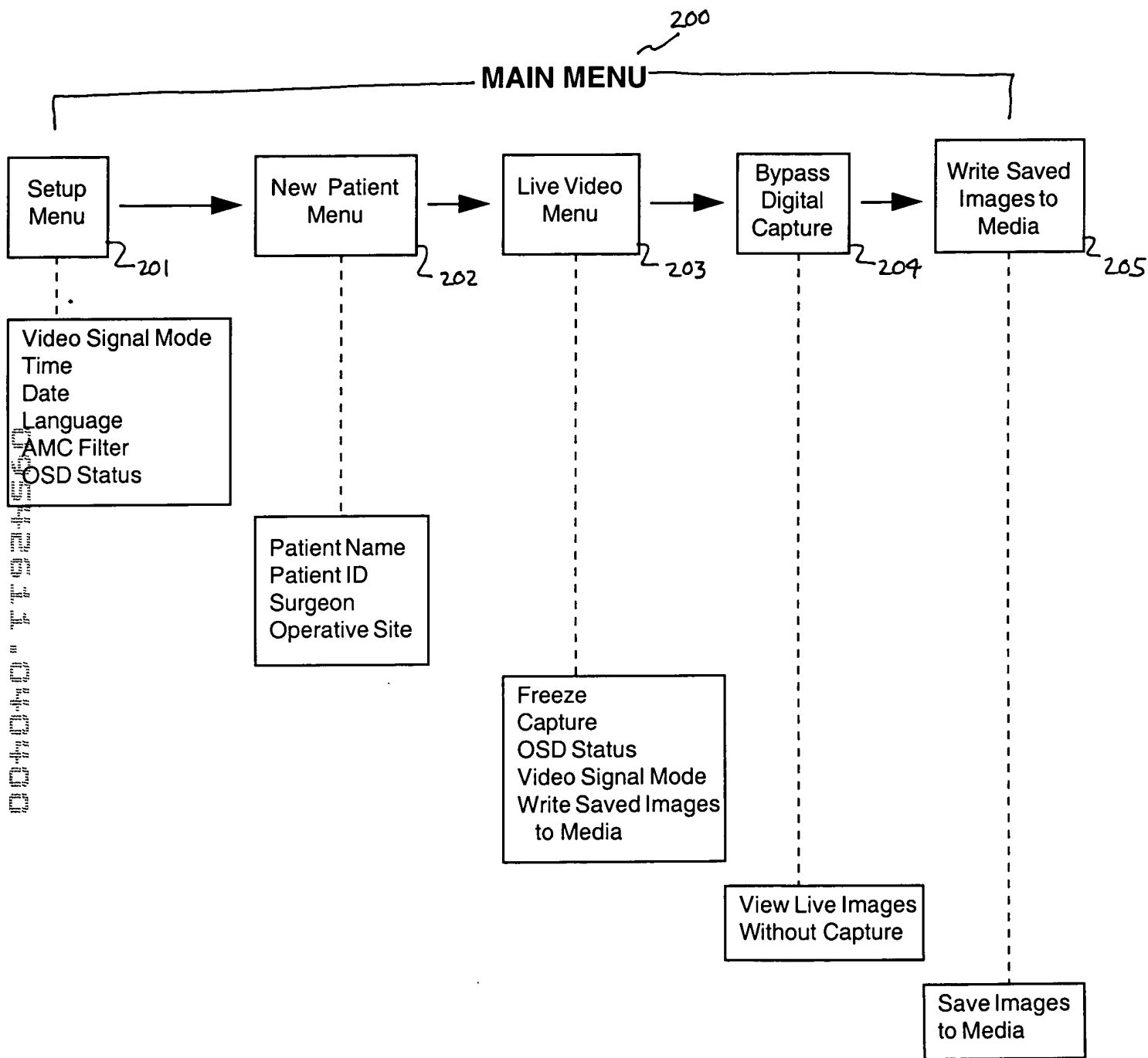


FIGURE 2

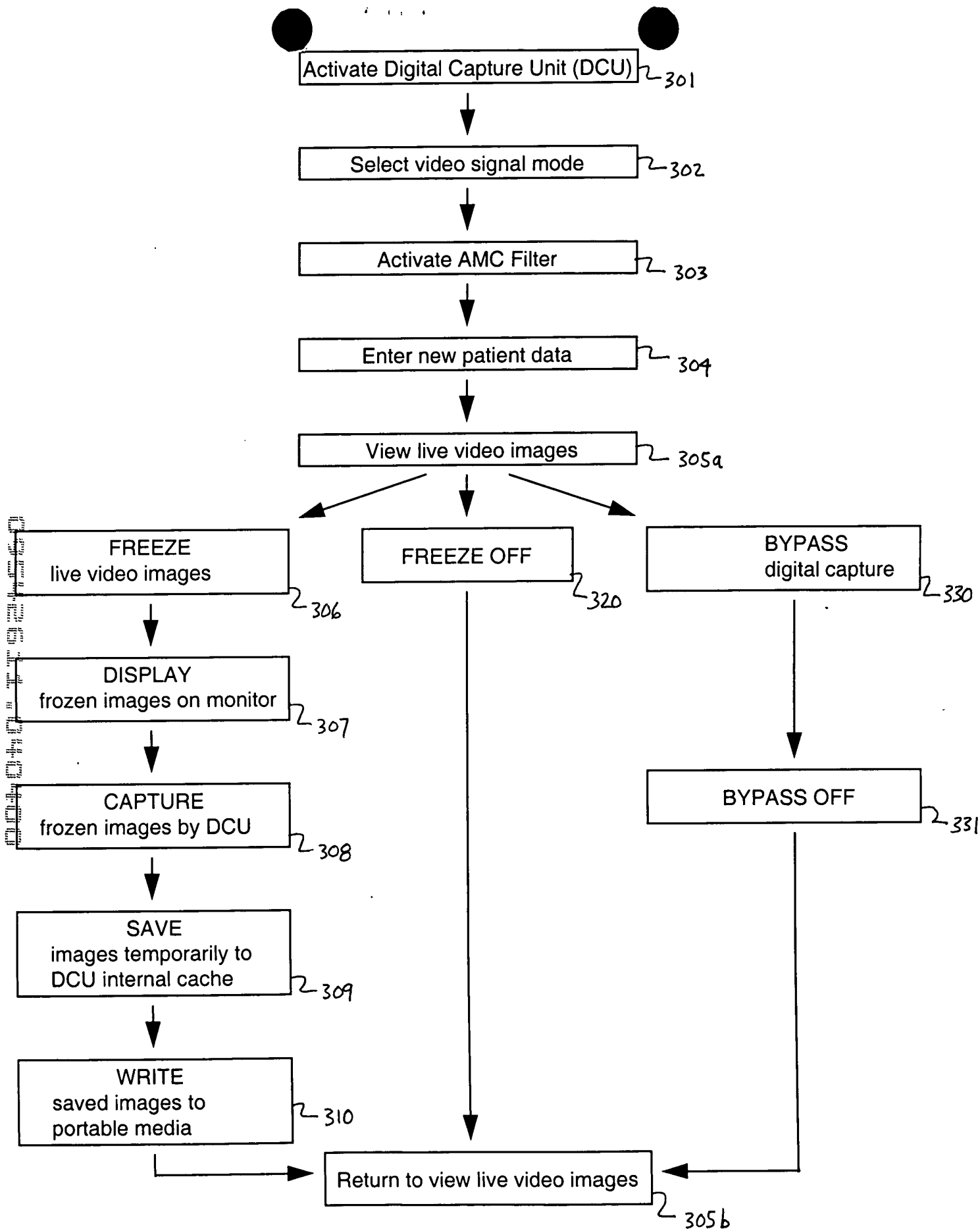


FIGURE 3

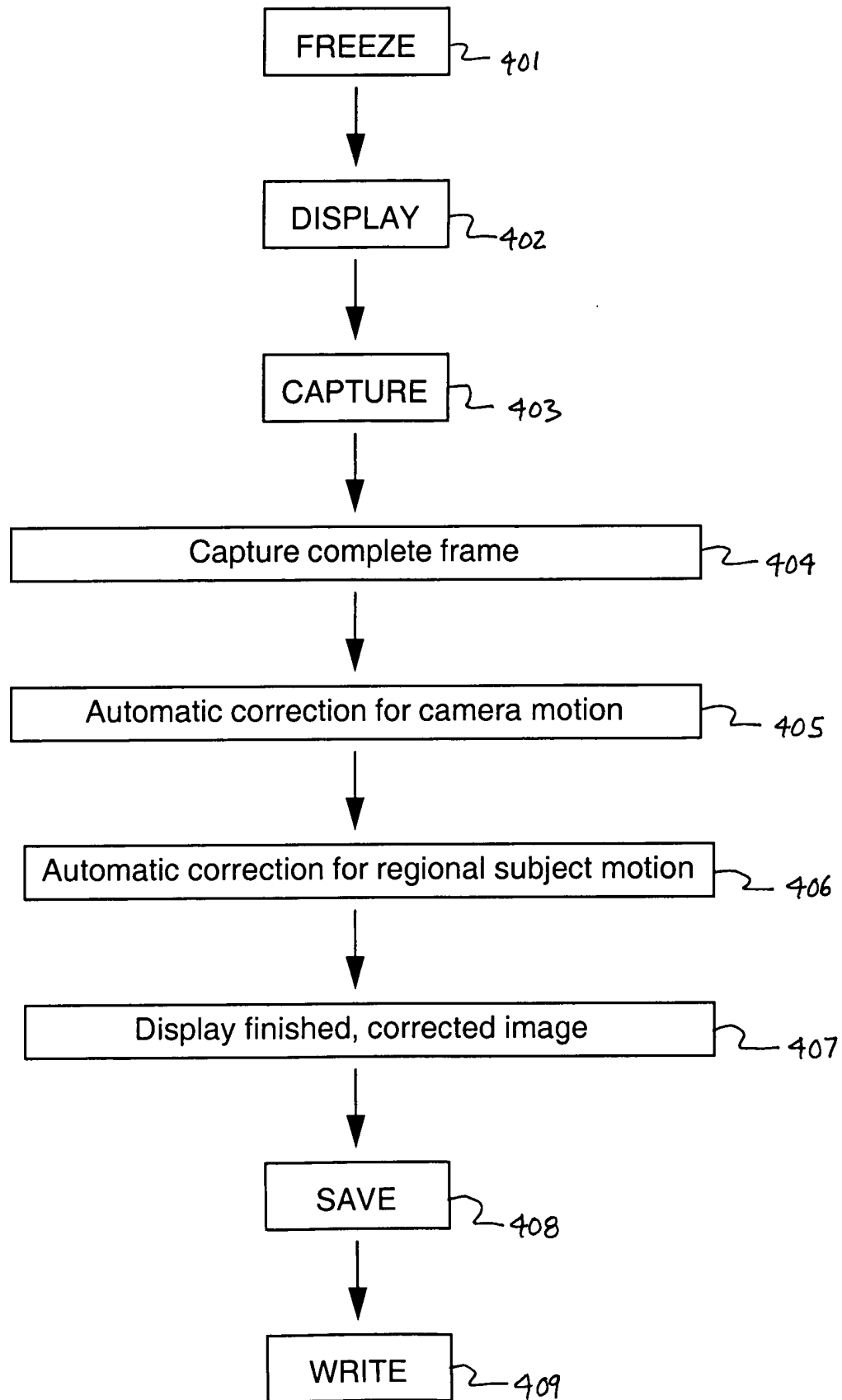


FIGURE 4

FRAME 1

Capture complete frame

501



MeasureMotionVector
Even/odd field motion vector

502



Convolution
Optimum raster auto-correlation

503



FRAME 2

ShiftEvenAndJoinOddField
Synthetic raster field

504



FRAME 3

LocateArtifacts
Subject motion map

505



FRAME 4

Decimate
Eliminate unwanted pixels

506



FRAME 5

Dialate
Adjust for eliminated pixels

507



FRAME 6

InterpolateMap
Compute even raster from odd raster

508



FRAME 7

Display finished corrected image

509

FIGURE 5

0354264.040400

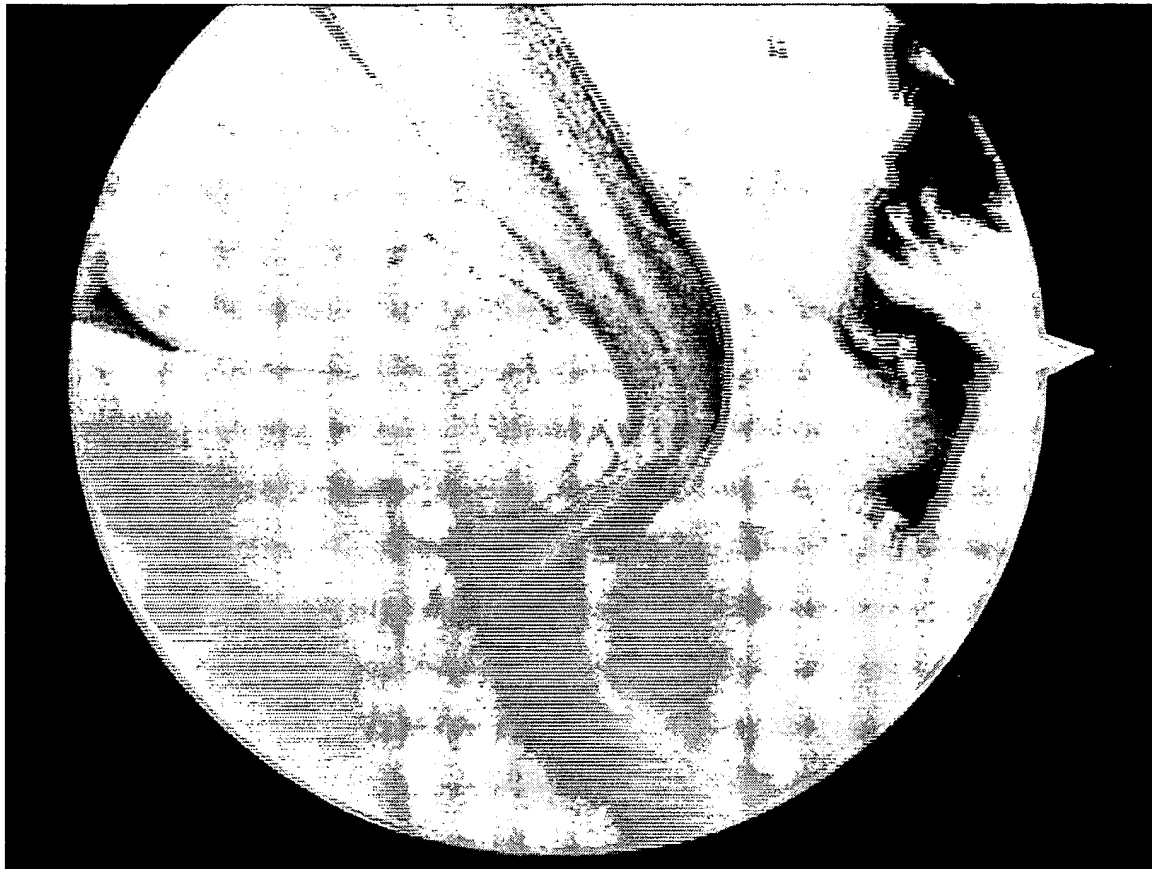


FIGURE 6

004040" 040400



FIGURE 7

004040" T 3450



FIGURE 8

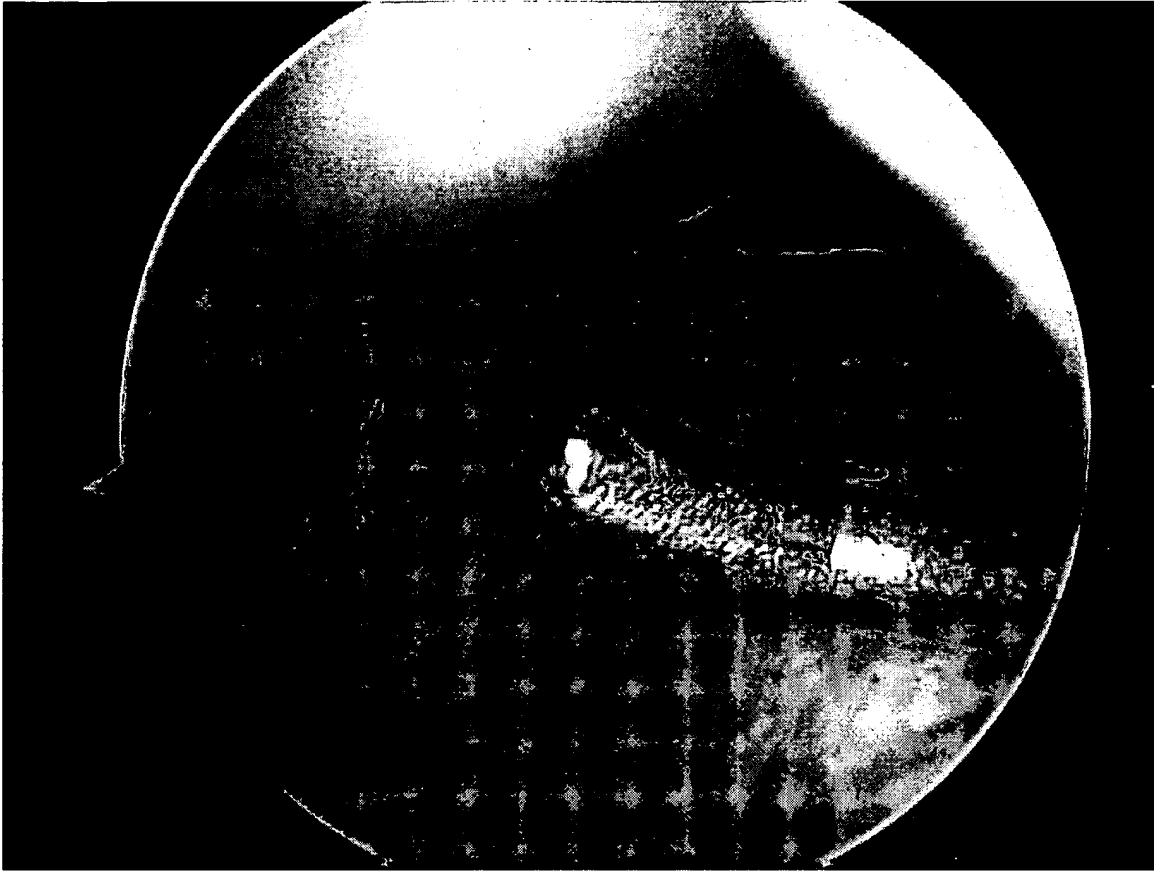


FIGURE 9

004040-040400